

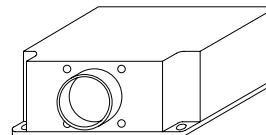
# MT941/4A

## μDAS Data Logger + 4 Analogue Channels



The μDAS (Micro DAS) data acquisition system is Magneti Marelli's entry level data logger. A light and extremely compact unit, it is ideal for applications where size and weight constraints are particularly severe.

Input to the data logger is via a CAN data bus from external add-on sensor modules together with speed and distance measurements provided by three internal input capture channels and 4 single-ended analogue 0-5V inputs. In the new memory structure, derived from the Formula 1 Black Box data logger, the data is split up into laps as it is recorded allowing individual laps to be downloaded as required. An improved serial port driver and an automatic download function provide quick and easy access to the data.



When combined with the Magneti Marelli MT940 programmable dashboard (4 analogue inputs) and Magneti Marelli engine control unit, it provides a simple and economic acquisition and control system for motor sports and in-vehicle testing. The modular nature of the μDAS architecture means that the system can be easily expanded to suit the exact user requirements, with the possibility to log up to a maximum of 63 channels via external CAN expansion modules.

### Technical data

#### Digital Inputs

Input Capture (wheel speed & RPM)  
wheel speed ..... IC1 & IC3  
RPM (pull-up to 12 V) ..... IC2  
Conversion ..... 4.34028 μs/LSB  
Threshold ..... 2 VMax Frequency  
(typical) ..... 9 kHz  
3 channels (typical) ..... (for each) 3 kHz  
Counter (distance) .....  
Source ..... IC1 & IC3  
Representation ..... 16-bit signed integer  
Track Marker .....  
re-arm delay ..... 10 s

#### Analogue Channels

No. .... 4  
Input Voltage ..... 0-5 V dc  
Input Impedance ..... >10 MΩ  
Input Filter ..... 1 pole 100 Hz  
Resolution ..... 10 bit  
Precision ..... ± 2 LSB  
Offset Error ..... 450 μV  
CMRR ..... 85 dB  
Over voltage Protection ..... ± 50V / 1 ms  
Tx data (CAN) ..... 200 Hz

#### Internal Channels

Compound Speed  
EITHER  
= mean(IC1 | IC3) IF Δvelocity < 3%  
OR  
= max (IC1 | IC3) IF Δvelocity > 3%

Compound Distance ..... 16-bit signed integer  
N.B. max distance counter value ..... 32767  
EITHER  
= mean(ΣIC1 & ΣIC3) IF Δvelocity < 3%  
OR  
= max (ΣIC1 | ΣIC3) IF Δvelocity > 3

#### Data Acquisition

Memory ..... 450 kByte  
Sampling freq. .... 1>100 Hz  
Channels ..... max 63  
Speed TX ..... max 57600 Baud

#### CAN Addresses (MT941/A only)

Data throughput (approx) ..... 15000 bytes/s  
..... Map1 ..... to ..... Map 8  
..... Default  
AIN1 ..... 60 ..... 88  
AIN2 ..... 61 ..... 89  
AIN3 ..... 62 ..... 90  
AIN4 ..... 63 ..... 91

#### Electrical / Mechanical

Supply ..... 8>18 V dc  
..... 130 mA  
Operating Temperature ..... -20+85 °C  
Shock ..... 50 g  
..... 10 ms  
Vibration ..... 10 g  
..... 0...500 Hz  
Dimensions ..... 84x33x105 mm  
Weight ..... 270 g  
Container ..... Black anodised aluminium IP66

### Ordering Information

Description	Order code
MT941/4A μDAS Data Logger + Data analysis SW + Flying connector with 4 S.E. analogue inputs	83816017100

default : μDAS = **CLOSED** ; 4 S.E. analogue internal module = **OPEN, addr. 84**

For further details please contact

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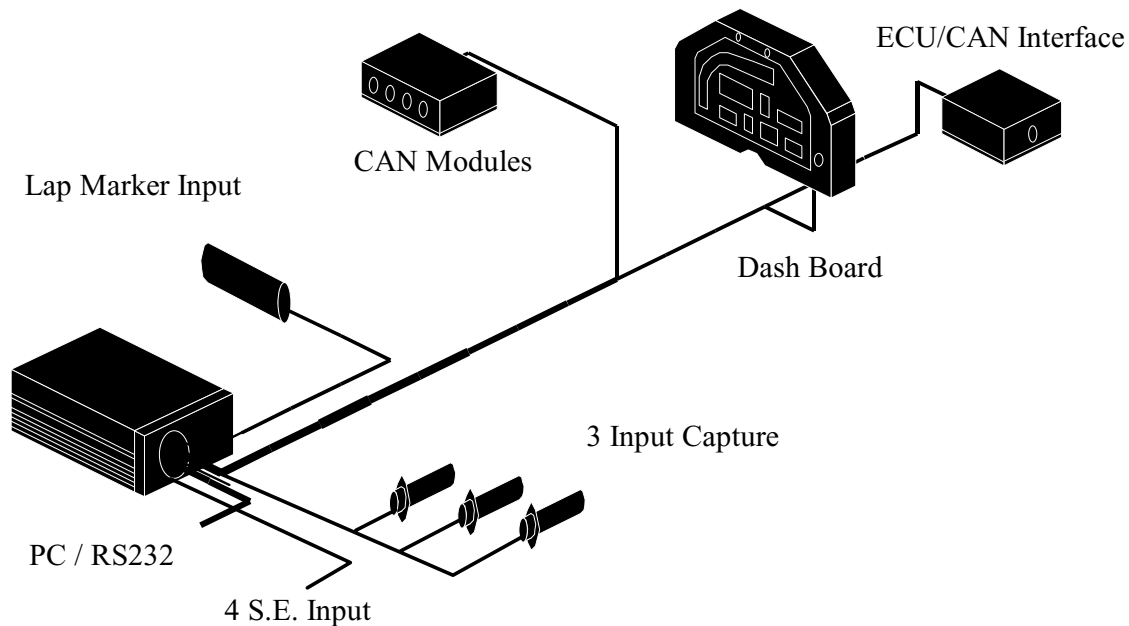
Fax: +44 (0)8707 444888  
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## Typical Configuration

The figure shows a schematic diagram of a basic data acquisition system. More complex systems can easily be built up using external sensor modules also available from Magneti Marelli.

Sensor data measured at the ECU and dashboard inputs is relayed to the  $\mu$ DAS over the CAN bus. Sampling frequencies, sensor linearisations and a start trigger are all configured via software prior to acquisition. Any of the channels available to the  $\mu$ DAS may be displayed on the dashboard. Engine RPM and two wheel speeds are measured directly by the logger. Measuring two wheel speeds allows the  $\mu$ DAS to compensate for wheel lock up and correct the speed and distance values derived from the pick-up (MT953) signals.

An optical (MT906/B & MT907/B) lap marker should be used to create fixed reference points in your race data.  $\mu$ DAS will partition the data into laps as it is recorded and save each lap time and number in a special header string. Having the data already organised into laps means that you can select and download individual laps of interest (or simply use the 'Best Lap' option to pick out the quickest one). Finally, an automatic download function saves you valuable time by triggering the data transfer as soon as the PC cable is connected and downloading only the latest data.

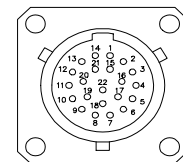


## Principal Features

- 450 Kbytes memory.
- Sampling frequencies up to 100 Hz
- CAN interface for connection to a wide range of expansion modules.
- Up to 63 independently programmable channels (byte or word) on CAN network.
- 4 x 5 V analogue inputs.
- Engine speed input.
- 2 wheel-speed inputs with intelligent wheel-lock correction algorithm.
- Track marker input.
- Memory architecture structured in laps.
- Bundled data analysis software WintaxJ for in-depth vehicle and engine performance monitoring.
- Data download to PC via serial RS232 at 57600 baud.

## Connector Pin Out

PIN	name	description
1	+ VBatt	Positive supply
2	Speed1	Input Capture 1
3	RPM	Input Capture 2
4	Speed2	Input Capture 3
5	Trag	Track marker i/p
6	WP	Code load (do not connect)
7	Can P	CAN positive
8	Can N	CAN negative
9	TX232	RS232
10	RX232	RS232
11>14	(AIN1..AIN4)	(Analog inputs 1 > 4)
15	Vref	Ref. voltage 5V d.c
16>22	GND	System GND



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